TECHNICASHEET



026 21

Description

This item controls resistive loads, ferromagnetic transformers and electronic transformers. After connecting the dimmer directly to the bus and the load, the brightness can be adjusted from any correctly configured control point. A quick pressure on local control key is enough to switch the load on or off, while an extended prewill adjust the light intensity. Actuator can signal any load faults such as a faultable and the load on the load faults such as a faultable and the load on the load on the load faultable and the load on the load on the load on the load faultable and the load on the load on

Technical data

100-240 @ 50/60 Hz
5 mA
ven loads:
1000 W/4.3 A
1000 W/16 A
nagnetic theogody Ames A
onic transforderA/4.3 A

Dimensional data

Size: 6 DIN modules

Legend

- 1. Configurator housing 7. OFF pushbutton for the
- Push&Learn pushbutton (future control/adjustment of the load application)
 8. Orange LED ON: load fault

7 6

3. SAV load control pushbutton Green LED ON: load active (from 1 %

5

- 4. Terminals for 230 Vac power $supply^{100 \%}$
- 5. Terminals for load 2
- 6. ON pushbutton for the
 - control/adjustment of the load

o () ON/-

4,3 A

98

9. RJ45 connector (male RJ45 adaptor for SCS BUS 488 72)

Configuration

The actuator performs all the basic operating modes which can be configured directly on the control. Moreover further operating modes with the same actuator are listed in the table below.

Possible function	Configurator in M
The actuator as Slave. Receives a control sent by a Master actuator w	/hich has the same addr ≦s &
Ignores the Room and General controls	PUL
Master Actuator with OFF control delayed on the corresponding Sla OFF control the Master actuator deactivates; the Slave actuator deac	

elapsed

1) The ONLY AND			
1) The ON control activates the Master actuator and the Slave actuator a t the same time. The next OFF control deactivates the Master actuator and keeps the Slave ac ር ቢያያርብ ሦር ቶየራ የbr the		Time (minutes)	
period of time set with configurator 1 – 4 inserted in M of the Master actuator as indicated ir the table. $\frac{1}{2}$	f the Master actµator as indicated in	1	
	2	2	
	3	3	
	4	4	-

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